## Anelta <br> DELTA ELECTRONICS, INC.

## IABU Headquarters

Delta Electronics, Inc.
31-1, Xingbang Road, Guishan Industrial Zone, Taoyuan County 33370, Taiwan, R.O.C.
TEL: 886-3-362-6301 / FAX: 886-3-362-726

Asia
Delta Electronics (Jiang Su) Ltd.
Wujiang Plant3
1688 Jiangxing East Road,
Wujiang Economic Development Zone
Wujiang City, Jiang Su Province,
People's Republic of China (Post code: 215200)
Delta Greentech (China) Co., Ltd
238 Min-Xia Road, Cao-Lu Industry Zone, Pudong, Shanghai eople's Republic of China
TEL: 021-58635678 / FAX: 021-58630003
Delta Electronics (Japan), Inc.
Delta Shibadaimon Building, 2-1-14
Shibadaimon, Minato-Ku, Tokyo, 105-0012,
Japan
TEL: 81-3-5733-1111 / FAX: 81-3-5733-1211
Delta Electronics (Korea), Inc.
234-9, Duck Soo Building 7F, Nonhyun-Dong,
Kangnam-Gu, Seoul, Korea 135-010
TEL: $82-2-515-5305 /$ /FAX: $82-2-515-530$
Delta Electronics (Singapore) Pte. Ltd
18 Ruby Warehouse Complex,
TEL: 65-6747-5155/FAX: 65-6744-9228
Delta Electronics (India) Pvt. Ltd.
lot No. 43, Sector - 35 , HSIIDC
Gurgaon 122001, Haryana, India
TEL: 91-124-416-9040/ FAX: 91-124-403-6045

## Americas

Delta Products Corporation (USA)
P.O. Box 12173,5101 Davis Drive,

Research Triangle Park, NC 27709, U.S.A.
TEL: 1-919-767-3813/FAX: 1-919-767-3969
Delta Greentech (Brasil) S/A
Sao Paulo Office
Rua Itapeva, $\mathrm{N}^{\circ} 26,3^{\circ}$ andar, Bela vista TEL:55-11-3568-3875/FAX:55-11-3568-386

## Europe

Deltronics (The Netherlands) B.V
Eindhoven Office De Witbogt 15,5652 AG Eindhoven, The Netherlands
TEL: 31-40-2592850/ FAX: 31-40-2592851

## (a) 5 Pal-A2 <br> Delta ASDA-A2 AC Servo System

## More Rapid, More Stable, More Precise

Delta Electronics, Inc., a leading manufacturer of industrial automation products, is pleased to announce the launch of its new high-performance ASDA-A2 series servo motors and servo drives with motion control.

The current trend for motion control has the control command source close to the drive. In response, Delta has developed The current trend for motion control has the control command source close to the drive. In response, Delta has developed
the new ASDA-A2 series that offers excellent motion control so that the external controller is almost eliminated. ASDA-A2 series features a built-in electronic cam (E-Cam) function which provides an excellent solution for flying shear, rotary cut and synchronized motion applications. The all new position register control PR mode is a unique and significant function that provides a variety of control modes to enhance system performance.

The advanced CANopen interface for high-speed communication enables the drive to integrate with other parts of the automation more efficiently and effectively. The full-closed control, auto notch filter, vibration suppression and gantry control functions help to perform complex motions that require high precision and smooth operation.

The 20-bit superior resolution encoder which is essential for accurate positioning applications is equipped as standard. In addition, the outstanding Capture and Compare functions for high-speed pulses offer the best support for stepless positioning. Other additional functionality, such as up to 1 kHz frequency response, innovative editing software and the high-speed PC monitoring function (similar to a digital oscilloscope), etc. all drastically maximize the performance of the ASDA-A2 series.

Delta's new ASDA-A2 series is the ultimate servo system providing a total solution for a wide range of machine tools and industrial applications


Table of Contents

|  | Page |
| :---: | :---: |
| 1. Introduction to the ASDA-A2 Series <br> Features <br> Product Line-up <br> Model Explanation | 1 |
| 2. ECMA Series Servo Motors <br> Features <br> Specifications <br> Dimensions <br> Speed-Torque Curves (T-N Curves) | 13 |
| 3. ASDA-A2 Series Servo Drives <br> Part Names and Functions <br> Standard Connection Examples <br> ASDA-Soft Configuration Software <br> Optional Accessories <br> Specifications <br> Dimensions <br> Servo Drive, Servo Motor and Accessories Comb | 27 |

4. Safety Information


## Introduction to the ASDA-A2 Series

## Features

- High Positioning Accuracy
- ECMA series servo motors feature incremental encoders with

20-bit resolution ( $1280000 \mathrm{p} / \mathrm{rev}$ ) which can eliminate unstabie commands at low speed, smooth motor operation and enhance the accuracy of positioning.

- Absolute encoder supported Motor position will not get lost when power is cut off.
- High Responsiveness
- Up to 1 kHz frequency response


Settling time below 1 ms

- 7 ms acceleration time for speeds from $-3000 \mathrm{r} / \mathrm{min}$ to $3000 \mathrm{r} / \mathrm{min}$ with an empty load! (Note: The test record of a 400 W motor with 60 mm frame size)


- Resonance Suppression
(High Frequency)
Two auto notch filters and one manual notch filter are provided to suppres mechanical resonance efficiently,



## Features

- Full-Closed Control Function
- Reduces the effects of backlash and flexibility from the machine and ensures the accuracy of positioning.

- Electronic Cam (E-Cam) Function
- 720 points max. for E-Cam outline
- Smooth interpolation between points can be completed automatically to yield a flexible programming.

ASDA-Soft configuration software supported

- Easy to use for flying shear, rotary cut, and other cam applications.


Insertion changes the command executed at the moment it is inserted

The second command is executed after the delay time or during the deceleration period.

 previous command is completed.

## - Versatile PR Mode

- ASDA-Soft configuration software supported.

New sub-modes supported, not traditional point-to-point control

- 64 procedures can be applied.
- Motion profile can be changed instantaneously
- 35 Homing modes / Jump mode/Write parameter mode/ Constant speed mode / Position control mode supported




## Introduction to the ASDA-A2 Series

## Product Line-up

220V Series


Product Line-up
400V Series
$\star$ ASDA-A2 $400 \mathrm{~V} 7.5 \mathrm{~kW}, 11 \mathrm{~kW}$ and 15 kW models will be available soon


11 . The boxes ( $\square$ ) at the ends of the servo drive model names are for optional configurations. For the actual model name, please refer to the model explanation of the 11 2. The boxes ( $\square$ ) in the servo motor model names are for optional configurations (keyway, brake and oil seal).

## MModel Explanation

- ASDA-A2 Series Servo Drives

- ECMA Series Servo Motors



## ECMA Series Servo Motors

## Features

ECMA series servo motors are permanent AC servo motors, capable of combining with 200 to 230 V ASDA-A2 220 V series AC servo drives from 100 W to 7.5 kW and 380 V to 480 V ASDA-A2 400 V series AC servo drives from 750 W to 5.5 kW .

For the 220 V series, there are $40 \mathrm{~mm}, 60 \mathrm{~mm}, 80 \mathrm{~mm}, 86 \mathrm{~mm}, 100 \mathrm{~mm}, 130 \mathrm{~mm}$ and 180 mm seven kinds of frame sizes available. The motor speed is from $1000 \mathrm{r} / \mathrm{min}$ to $5000 \mathrm{r} / \mathrm{min}$ and the torque output is from $1.92 \mathrm{~N}-\mathrm{m}$ to $119.36 \mathrm{~N}-\mathrm{m}$.

For the 400 V series, there are $80 \mathrm{~mm}, 130 \mathrm{~mm}$ and 180 mm three kinds of frame sizes available. The motor speed is from $1500 \mathrm{r} / \mathrm{min}$ to $5000 \mathrm{r} / \mathrm{min}$ and the torque output is from $2.39 \mathrm{~N}-\mathrm{m}$ to $119.36 \mathrm{~N}-\mathrm{m}$.

In terms of optional configurations, ECMA series provides brake and oil seal to fully support our customers' needs. It also offers two different shaft selections, round shaft and keyway, for various applications.


## 220V Series

| ECMA Series | C104 | C106 |  | C108 |  | C109 |  | C110 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 01 | 02 | 04 | 04 | 07 | 07 | 10 | 10 | 20 |
| Rated output power (kW) | 0.1 | 0.2 | 0.4 | 0.4 | 0.75 | 0.75 | 1.0 | 1.0 | 2.0 |
| Rated torque ( $\mathrm{N}-\mathrm{m})^{11}$ | 0.32 | 0.64 | 1.27 | 1.27 | 2.39 | 2.39 | 3.18 | 3.18 | 6.37 |
| Maximum torque ( N -m) | 0.96 | 1.92 | 3.82 | 3.82 | 7.16 | 7.14 | 8.78 | 9.54 | 19.11 |
| Rated speed (r/min) | 3000 |  |  |  |  | 3000 |  | 3000 |  |
| Maximum speed (r/min) | 5000 |  |  |  |  | 3000 |  | 5000 |  |
| Rated current (A) | 0.90 | 1.55 | 2.6 | 2.6 | 5.1 | 3.66 | 4.25 | 7.3 | 12.05 |
| Maximum current (A) | 2.70 | 4.65 | 7.8 | 7.24 | 15.3 | 11 | 12.37 | 21.9 | 36.15 |
| Power rating (kW/s) | 27.7 | 22.4 | 57.6 | 22.1 | 48.4 | 29.6 | 38.6 | 38.1 | 90.6 |
| $\begin{gathered} \hline \text { Rotor moment of inertia } \\ \left(\times 10^{-1} \mathrm{~kg}-\mathrm{m}^{2}\right) \\ \hline \end{gathered}$ | 0.037 | 0.177 | 0.277 | 0.68 | 1.13 | 1.93 | 2.62 | 2.65 | 4.45 |
| Mechanical time constant (ms) | 0.75 | 0.80 | 0.53 | 0.73 | 0.62 | 1.72 | 1.20 | 0.74 | 0.61 |
| Torque constant-KT ( $\mathrm{N}-\mathrm{m} / \mathrm{A}$ ) | 0.36 | 0.41 | 0.49 | 0.49 | 0.47 | 0.65 | 0.75 | 0.44 | 0.53 |
| Voltage constant-KE(mV/r/min)) | 13.6 | 16 | 17.4 | 18.5 | 17.2 | 27.5 | 24.2 | 16.8 | 19.2 |
| Armature resistance (0hm) | 9.30 | 2.79 | 1.55 | 0.93 | 0.42 | 1.34 | 0.897 | 0.20 | 0.13 |
| Armature inductance ( mH ) | 24.0 | 12.07 | 6.71 | 7.39 | 3.53 | 7.55 | 5.7 | 1.81 | 1.50 |
| Electrical time constant (ms) | 2.58 | 4.3 | 4.3 | 7.96 | 8.36 | 5.66 | 6.35 | 9.3 | 11.4 |
| Insulation class | Class A (UL), Class B (CE) |  |  |  |  |  |  |  |  |
| Insulation resistance | 100M $\Omega$, DC 500V |  |  |  |  |  |  |  |  |
| Insulation strength | AC $1500 \mathrm{~V}, 60$ seconds |  |  |  |  |  |  |  |  |
| Weight (kg) (without brake) | 0.5 | 1.2 | 1.6 | 2.1 | 3.0 | 2.9 | 3.8 | 4.3 | 6.2 |
| Weight (kg) (with brake) | 0.8 | 1.5 | 2.0 | 2.9 | 3.8 | 3.69 | 5.5 | 4.7 | 7.2 |
| Max. radial shaft load (N) | 78.4 | 196 | 196 | 245 | 245 | 245 | 245 | 490 | 490 |
| Max. thrust shaft load (N) | 39.2 | 68 | 68 | 98 | 98 | 98 | 98 | 98 | 98 |
| Power rating (kW/s) (with brake) | 25.6 | 21.3 | 53.8 | 22.1 | 48.4 | 29.3 | 37.9 | 30.4 | 82 |
| Rotor moment of inertia (Kg.m²) (with brake) | 0.04 | 0.192 | 0.30 | 0.73 | 1.18 | 1.95 | 2.67 | 3.33 | 4.95 |
| Mechanical time constant (ms) (with brake) | 0.81 | 0.85 | 0.57 | 0.78 | 0.65 | 1.74 | 1.22 | 0.93 | 0.66 |
| Brake holding torque [ $\mathrm{Nt-m}(\mathrm{~min})]$ | 0.3 | 1.3 | 1.3 | 2.5 | 2.5 | 2.5 | 2.5 | 8 | 8 |
| Brake power consumption (at $20^{\circ} \mathrm{C}$ [W] | 7.2 | 6.5 | 6.5 | 8.2 | 8.2 | 8.2 | 8.2 | 18.5 | 18.5 |
| Brake release time [ms (Max)] | 5 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 10 |
| Brake pull-in time [ms (Max)] | 25 | 70 | 70 | 70 | 70 | 70 | 70 | 70 | 70 |
| Vibration grade ( $\mu \mathrm{m}$ ) | 15 |  |  |  |  |  |  |  |  |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ) | $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ ( $32^{\circ} \mathrm{F}$ to $104^{\circ} \mathrm{F}$ ) |  |  |  |  |  |  |  |  |
| Storage temperature ( ${ }^{\circ} \mathrm{C}$ ) | $-10^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}\left(-14^{\circ} \mathrm{F}\right.$ to $\left.176{ }^{\circ} \mathrm{F}\right)$ |  |  |  |  |  |  |  |  |
| Operating humidity | 20 to 90\%RH (non-condensing) |  |  |  |  |  |  |  |  |
| Storage humidity | 20 to 90\%RH (non-condensing) |  |  |  |  |  |  |  |  |
| Vibration capacity | 2.5 G |  |  |  |  |  |  |  |  |
| IP Rating | IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used)) |  |  |  |  |  |  |  |  |
| Approvals | ce c~Mus |  |  |  |  |  |  |  |  |

[^0]ECMA Series Servo Motors

Specifications - Medium / High Inertia Series
220 V Series

| Model: ECMA Series | E113 |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 05 | 10 | 15 | 20 |
| Rated output power (kW) | 0.5 | 1.0 | 1.5 | 2.0 |
| Rated torque ( $\mathrm{N}-\mathrm{m}$ ) | 2.39 | 4.77 | 7.16 | 9.55 |
| Maximum torque ( $\mathrm{N}-\mathrm{m}$ ) | 7.16 | 14.32 | 21.48 | 28.65 |
| Rated speed (r/min) | 2000 |  |  |  |
| Maximum speed (r/min) | 3000 |  |  |  |
| Rated current (A) | 2.9 | 5.6 | 8.3 | 11.01 |
| Maximum current ( A ) | 8.7 | 16.8 | 24.81 | 33 |
| Power rating (kW/s) | 7.0 | 27.1 | 45.9 | 62.5 |
| $\begin{gathered} \text { Rotor moment of inertia } \\ \left(\times 10^{-1} \mathrm{~kg} \cdot \mathrm{~m}^{2}\right) \text { (without brake) } \end{gathered}$ | 8.17 | 8.41 | 11.18 | 14.59 |
| Mechanical time constant (ms) | 1.91 | 1.51 | 1.11 | 0.96 |
| Torque constant-KT ( N -m/A) | 0.83 | 0.85 | 0.87 | 0.87 |
| Voltage constant-KE (mV/(r/min)) | 30.9 | 31.9 | 31.8 | 31.8 |
| Armature resistance (Ohm) | 0.57 | 0.47 | 0.26 | 0.174 |
| Armature inductance (mH) | 7.39 | 5.99 | 4.01 | 2.76 |
| Electrical time constant (ms) | 12.96 | 12.88 | 15.31 | 15.86 |
| Insulation class | Class A (UL), Class B (CE) |  |  |  |
| Insulation resistance | 100M $\Omega$, DC500V |  |  |  |
| Insulation strength | AC $1500 \mathrm{~V}, 60$ seconds |  |  |  |
| Weight (kg) (without brake) | 6.8 | 7 | 7.5 | 7.8 |
| Weight (kg) (with brake) | 8.2 | 8.4 | 8.9 | 9.2 |
| Max. radial shaft load ( N ) | 490 | 490 | 490 | 490 |
| Max. thrust shaft load (N) | 98 | 98 | 98 | 98 |
| Power rating (kW/s) (with brake) | 6.4 | 24.9 | 43.1 | 59.7 |
| Rotor moment of finertia $\left(\times 10^{\circ} \mathrm{kg} . \mathrm{m}^{2}\right)($ with brake $)$ | 8.94 | 9.14 | 11.90 | 15.88 |
| Mechanical time constant (ms) (with brake) | 2.07 | 1.64 | 1.19 | 1.05 |
| Brake holding torque [Nt-m (min)] | 10.0 | 10.0 | 10.0 | 10.0 |
| Brake power consumption (at $20^{\circ} \mathrm{C}$ [W] | 19.0 | 19.0 | 19.0 | 19.0 |
| Brake release time [ms (Max)] | 10 | 10 | 10 | 10 |
| Brake pull-in time [ms (Max)] | 70 | 70 | 70 | 70 |
| Vibration grade ( $\mu \mathrm{m}$ ) | 15 |  |  |  |
| Operating temperature ( ${ }^{\text {C }}$ ) | $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ ( $32^{\circ} \mathrm{F}$ to $104^{\circ} \mathrm{F}$ ) |  |  |  |
| Storage temperature ( ${ }^{\circ} \mathrm{C}$ ) | $-10^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}\left(-14{ }^{\circ} \mathrm{F}\right.$ to $176{ }^{\circ} \mathrm{F}$ ) |  |  |  |
| Operating humidity | 20 to 90\%RH (non-condensing) |  |  |  |
| Storage humidity | 20 to 90\%RH (non-condensing) |  |  |  |
| Vibration capacity | 2.5 G |  |  |  |
| IP Rating | IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used)) |  |  |  |
| Approvals | ce c-Mus |  |  |  |

S Specifications - Medium / High Inertia Series

## 220V Series

| Model: ECMA Series | E118 |  | G113 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 20 | 30 | 03 | 06 | 09 |
| Rated output power (kW) | 2.0 | 3.0 | 0.3 | 0.6 | 0.9 |
| Rated torque ( $\mathrm{N}-\mathrm{m})^{-1}$ | 9.55 | 14.32 | 2.86 | 5.73 | 8.59 |
| Maximum torque ( $\mathrm{N}-\mathrm{m}$ ) | 28.65 | 42.97 | 8.59 | 17.19 | 21.48 |
| Rated speed (r/min) | 2000 |  | 1000 |  |  |
| Maximum speed (r/min) | 3000 |  | 2000 |  |  |
| Rated current (A) | 11.22 | 16.1 | 2.5 | 4.8 | 7.5 |
| Maximum current (A) | 33.66 | 48.3 | 7.44 | 14.49 | 22.5 |
| Power rating (kW/s) | 26.3 | 37.3 | 10.0 | 39.0 | 66.0 |
| $\begin{gathered} \text { Rotor moment of inertia } \\ \left(\times 10^{\mathrm{k}} \mathrm{~kg} \cdot \mathrm{~m}^{2}\right) \text { (without brake) } \\ \hline \end{gathered}$ | 34.68 | 54.95 | 8.17 | 8.41 | 11.18 |
| Mechanical time constant (ms) | 1.62 | 1.06 | 1.84 | 1.40 | 1.07 |
| Torque constant-KT ( $\mathrm{N}-\mathrm{m} / \mathrm{A}$ ) | 0.85 | 0.89 | 1.15 | 1.19 | 1.15 |
| Voltage constant-KE (mV/(r/min)) | 31.4 | 32 | 42.5 | 43.8 | 41.6 |
| Armature resistance (Ohm) | 0.119 | 0.052 | 1.06 | 0.82 | 0.43 |
| Armature inductance ( mH ) | 2.84 | 1.38 | 14.29 | 11.12 | 6.97 |
| Electrical time constant (ms) | 23.87 | 26.39 | 13.55 | 13.55 | 16.06 |
| Insulation class | Class A (UL), Class B (CE) |  |  |  |  |
| Insulation resistance | 100M 2 , DC 500V |  |  |  |  |
| Insulation strength | AC $1500 \mathrm{~V}, 60$ seconds |  |  |  |  |
| Weight (kg) (without brake) | 13.5 | 18.5 | 6.8 | 7 | 7.5 |
| Weight (kg) (with brake) | 17.5 | 22.5 | 8.2 | 8.4 | 8.9 |
| Max. radial shaft load (N) | 1176 | 1470 | 490 | 490 | 490 |
| Max. thrust shaft load (N) | 490 | 490 | 98 | 98 | 98 |
| Power rating (kW/s) (with brake) | 24.1 | 35.9 | 9.2 | 35.9 | 62.1 |
| Rotor moment of inertia ( $\times 10^{-4} \mathrm{~kg} . \mathrm{m}^{2}$ )(with brake) | 37.86 | 57.06 | 8.94 | 9.14 | 11.9 |
| Mechanical time constant (ms) (with brake) | 1.77 | 1.10 | 2.0 | 1.51 | 1.13 |
| Brake holding torque [Nt-m (min)] | 25.0 | 25.0 | 10.0 | 10.0 | 10.0 |
| Brake power consumption (at $20^{\circ} \mathrm{C}$ ) WW ] | 20.4 | 20.4 | 19.0 | 19.0 | . 0 |
| Brake release time [ms (Max)] | 10 | 10 | 10 | 10 | 10 |
| Brake pull-in time [ms (Max)] | 70 | 70 | 70 | 70 | 70 |
| Vibration grade ( $\mu \mathrm{m}$ ) | 15 |  |  |  |  |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ) | $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ ( $32^{\circ} \mathrm{F}$ to $104^{\circ} \mathrm{F}$ ) |  |  |  |  |
| Storage temperature ( ${ }^{\circ} \mathrm{C}$ ) | $-10^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}\left(-14^{\circ} \mathrm{F}\right.$ to $\left.176{ }^{\circ} \mathrm{F}\right)$ |  |  |  |  |
| Operating humidity | 20 to $90 \% \mathrm{RH}$ (non-condensing) |  |  |  |  |
| Storage humidity | 20 to $90 \% \mathrm{RH}$ (non-condensing) |  |  |  |  |
| Vibration capacity | 2.5 G |  |  |  |  |
| IP Rating | IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used)) |  |  |  |  |
| Approvals | $c \in \quad c \geqslant M_{u s}$ |  |  |  |  |

[^1]

Specifications - Medium / Medium-High Inertia Series

## 220V Series

| Model: ECMA Series | F118 |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 30 | 45 | 55 | 75 |
| Rated output power (kW) | 3.0 | 4.5 | 5.5 | 7.5 |
| Rated torque ( $\mathrm{N}-\mathrm{m})^{\text {\% }}$ | 19.10 | 28.65 | 35.01 | 47.74 |
| Maximum torque ( $\mathrm{N}-\mathrm{m}$ ) | 57.29 | 71.62 | 87.53 | 119.36 |
| Rated speed (r/min) | 1500 |  |  |  |
| Maximum speed (r/min) | 3000 |  |  |  |
| Rated current (A) | 19.4 | 32.5 | 40.0 | 47.5 |
| Maximum current ( A ) | 58.2 | 81.3 | 100.0 | 118.8 |
| Power rating (kW/s) | 66.4 | 105.5 | 122.9 | 159.7 |
| Rotor moment of inertia $\left(\times 10^{-1} \mathrm{~kg} \cdot \mathrm{~m}^{2}\right)$ (without brake) | 54.95 | 77.75 | 99.78 | 142.7 |
| Mechanical time constant (ms) | 1.28 | 0.92 | 0.96 | 0.63 |
| Torque constant-KT ( N -m/A) | 0.98 | 0.88 | 0.88 | 1.01 |
| Voltage constant-KE (mV/(r/min)) | 35.0 | 32.0 | 31.0 | 35.5 |
| Armature resistance (Ohm) | 0.077 | 0.032 | 0.025 | 0.015 |
| Armature inductance (mH) | 1.27 | 0.89 | 0.60 | 0.40 |
| Electrical time constant (ms) | 16.5 | 27.8 | 24.0 | 26.7 |
| Insulation class | Class A (UL), Class B (CE) |  |  |  |
| Insulation resistance | 100M 2 , DC 500V |  |  |  |
| Insulation strength | AC $1500 \mathrm{~V}, 60$ seconds |  |  |  |
| Weight (kg) (without brake) | 18.5 | 23.5 | 30.5 | 40.5 |
| Weight (kg) (with brake) | 22.5 | 29 | 36 | 46 |
| Max. radial shaft load ( N ) | 1470 | 1470 | 1764 | 1764 |
| Max. thrust shaft load ( N ) | 490 | 490 | 588 | 588 |
| Power rating (kW/s) (with brake) | 63.9 | 101.8 | 119.4 | 156.6 |
| Rotor moment of inertia ( $\times 10^{-4} \mathrm{~kg} \cdot \mathrm{~m}^{2}$ )(with brake) | 57.06 | 80.65 | 102.70 | 145.55 |
| Mechanical time constant ( ms ) (with brake) | 1.33 | 0.96 | 0.99 | 0.64 |
| Brake holding torque [Nt-m (min)] | 25.0 | 25.0 | 25.0 | 25.0 |
| Brake power consumption $\left(\right.$ at $\left.20^{\circ} \mathrm{C}\right)[\mathrm{W}]$ | 20.4 | 20.4 | 20.4 | 20.4 |
| Brake release time [ms (Max)] | 10 | 10 | 10 | 10 |
| Brake pull-in time [ms (Max)] | 70 | 70 | 70 | 70 |
| Vibration grade ( $\mu \mathrm{m}$ ) | 15 |  |  |  |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ) | $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ ( $32^{\circ} \mathrm{F}$ to $104^{\circ} \mathrm{F}$ ) |  |  |  |
| Storage temperature ( ${ }^{\circ} \mathrm{C}$ ) | $-10^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}\left(-14^{\circ} \mathrm{F}\right.$ to $\left.176^{\circ} \mathrm{F}\right)$ |  |  |  |
| Operating humidity | 20 to $90 \% \mathrm{RH}$ (non-condensing) |  |  |  |
| Storage humidity | 20 to $90 \% \mathrm{RH}$ (non-condensing) |  |  |  |
| Vibration capacity | 2.5 G |  |  |  |
| IP Rating | IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to therotating shaft (an oil seal model is used)) |  |  |  |
| Approvals | ce c~1 us |  |  |  |



[^2]
## Specifications - Medium / Low Inertia Series

## 400V Series

| Model: ECMA Series | $J 108$ | K113 |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 07 | 10 | 15 | 20 |
| Rated output power (kW) | 0.75 | 1.0 | 1.5 | 2.0 |
| Rated torque ( $\mathrm{N}-\mathrm{m}$ ) ${ }^{\text {chen}}$ | 2.39 | 4.77 | 7.16 | 9.55 |
| Maximum torque ( $\mathrm{N}-\mathrm{m}$ ) | 7.16 | 14.32 | 21.48 | 28.65 |
| Rated speed (r/min) | 3000 |  | 2000 |  |
| Maximum speed (r/min) | 5000 |  | 3000 |  |
| Rated current (A) | 3.07 | 3.52 | 5.02 | 6.66 |
| Maximum current (A) | 9.5 | 10.56 | 15.06 | 19.98 |
| Power rating (kW/s) | 50.4 | 27.1 | 45.9 | 62.5 |
| $\begin{gathered} \text { Rotor moment of inertia } \\ \left(\times 10^{4} \mathrm{~kg} \cdot \mathrm{~m}^{2}\right) \text { (without brake) } \end{gathered}$ | 1.13 | 8.41 | 11.18 | 14.59 |
| Mechanical time constant (ms) | 0.66 | 1.80 | 1.24 | 1.04 |
| Torque constant-KT ( $\mathrm{N}-\mathrm{m} / \mathrm{A}$ ) | 0.78 | 1.35 | 1.43 | 1.43 |
| Voltage constant-KE (mV/(r/min)) | 28.24 | 53.2 | 55 | 55 |
| Armature resistance (Ohm) | 1.22 | 1.47 | 0.83 | 0.57 |
| Armature inductance ( mH ) | 10.68 | 17.79 | 11.67 | 8.29 |
| Electrical time constant (ms) | 8.75 | 12.04 | 14.04 | 14.39 |
| Insulation class | --- |  |  |  |
| Insulation resistance | 100M 2 , DC 500V |  |  |  |
| Insulation strength | AC $1800 \mathrm{~V}, 60$ seconds |  |  |  |
| Weight (kg) (without brake) | 3.0 | 7.0 | 7.5 | 7.8 |
| Weight (kg) (with brake) | 3.8 | 8.4 | 8.9 | 9.2 |
| Max. radial shaft load ( N ) | 245 | 490 | 490 | 490 |
| Max. thrust shaft load (N) | 98 | 98 | 98 | 98 |
| Power rating (kW/s) (with brake) | 48.4 | 24.9 | 43.1 | 59.7 |
| Rotor moment of inertia ( $\times 10^{4} \mathrm{~kg} \cdot \mathrm{~m}^{2}$ )(with brake) | 1.18 | 9.14 | 11.90 | 15.88 |
| Mechanical time constant (ms) (with brake) | 0.65 | 1.96 | 1.32 | 1.13 |
| Brake holding torque [ $\mathrm{Nt-m}(\mathrm{~min})]$ | 2.5 | 10.0 | 10.0 | 10.0 |
| Brake power consumption (at $20^{\circ} \mathrm{C}$ ) WW$]$ | 8.5 | 19.0 | 19.0 | 19.0 |
| Brake release time [ms (Max)] | 10 | 10 | 10 | 10 |
| Brake pull-in time [ms (Max)] | 70 | 70 | 70 | 70 |
| Vibration grade ( $\mu \mathrm{m}$ ) | 15 |  |  |  |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ) | $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}$ ( $32^{\circ} \mathrm{F}$ to $104^{\circ} \mathrm{F}$ ) |  |  |  |
| Storage temperature ( ${ }^{\circ} \mathrm{C}$ ) | $-10^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ ( $-14^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}$ ) |  |  |  |
| Operating humidity | 20 to $90 \% \mathrm{RH}$ (non-condensing) |  |  |  |
| Storage humidity | 20 to $90 \% \mathrm{RH}$ (non-condensing) |  |  |  |
| Vibration capacity | 2.5 G |  |  |  |
| IP Rating | IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used)) |  |  |  |
| Approvals | ce c~Mus |  |  |  |

Specifications - Medium / High Inertia Series
400V Series

| Model: ECMA Series | L118 |  |  |
| :---: | :---: | :---: | :---: |
|  | 30 | 45 | 55 |
| Rated output power (kW) | 3.0 | 4.5 | 5.5 |
| Rated torque ( $\mathrm{N}-\mathrm{m})^{\text {- }}$ | 19.10 | 28.65 | 35.0 |
| Maximum torque ( $\mathrm{N}-\mathrm{m}$ ) | 57.29 | 71.62 | 87.53 |
| Rated speed (r/min) | 1500 |  |  |
| Maximum speed (r/min) | 3000 |  |  |
| Rated current (A) | 11.9 | 20.0 | 22.37 |
| Maximum current ( A ) | 35.7 | 50 | 56 |
| Power rating (kW/s) | 66.4 | 105.5 | 122.9 |
| $\begin{gathered} \text { Rotor moment of inertia } \\ \left(\times 10^{4} \mathrm{~kg} \cdot \mathrm{~m}^{2}\right)(\text { without brake }) \\ \hline \end{gathered}$ | 54.95 | 77.75 | 99.78 |
| Mechanical time constant (ms) | 1.11 | 0.92 | 0.88 |
| Torque constant-KT ( $\mathrm{N}-\mathrm{m} / \mathrm{A}$ ) | 1.66 | 1.43 | 1.50 |
| Voltage constant-KE (mV/(r/min)) | 60.54 | 55.63 | 57.99 |
| Armature resistance (Ohm) | 0.19 | 0.09 | 0.07 |
| Armature inductance ( mH ) | 4.8 | 2.7 | 2.55 |
| Electrical time constant (ms) | 24.7 | 30 | 31.7 |
| Insulation class | --- |  |  |
| Insulation resistance | $100 \mathrm{M} \Omega$, DC 500 V |  |  |
| Insulation strength | AC $1800 \mathrm{~V}, 50 \mathrm{~Hz}, 60$ seconds |  |  |
| Weight (kg) (without brake) | 18.5 | 23.5 | 30.5 |
| Weight (kg) (with brake) | 22.5 | 29 | 36 |
| Max. radial shaft load ( N ) | 1470 | 1470 | 1764 |
| Max. thrust shaft load ( N ) | 490 | 490 | 588 |
| Power rating (kW/s) (with brake) | 63.9 | 101.8 | 119.1 |
| Rotor moment ofinertia ( $\times 10^{-4} \mathrm{~kg} . \mathrm{m}^{2}$ )(with brake) | 57.06 | 80.65 | 102.70 |
| Mechanical time constant (ms) (with brake) | 1.16 | 0.95 | 0.91 |
| Brake holding torque [Nt-m (min)] | 25.0 | 40.0 | 55.0 |
| Brake power consumption (at $20^{\circ} \mathrm{C}$ [ W$]$ | 20.4 | 15.1 | 21 |
| Brake release time [ms (Max)] | 10 | 10 | 10 |
| Brake pull-in time [ms (Max)] | 70 | 70 | 70 |
| Vibration grade ( $\mu \mathrm{m}$ ) | 15 |  |  |
| Operating temperature ( ${ }^{\text {C }}$ ) | $0^{\circ} \mathrm{C}$ to $40^{\circ} \mathrm{C}\left(32^{\circ} \mathrm{F}\right.$ to $\left.104^{\circ} \mathrm{F}\right)$ |  |  |
| Storage temperature ( ${ }^{\circ} \mathrm{C}$ ) | $-10^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}\left(-14^{\circ} \mathrm{F}\right.$ to $176{ }^{\circ} \mathrm{F}$ ) |  |  |
| Operating humidity | 20 to $90 \%$ RH (non-condensing) |  |  |
| Storage humidity | 20 to 90\%RH (non-condensing) |  |  |
| Vibration capacity | 2.5 G |  |  |
| IP Rating | IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used)) |  |  |
| Approvals | ce c~Mus |  |  |

## Dimensions

## 220 V Series

Frame Size 80 mm and below (Units: mm)


| Model | C10401■ ${ }^{\text {S }}$ | C10602■S | C10604■S | C10804 $\square^{7}$ | C10807■S | C10907■S | C10910 $\square$ S |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LC | 40 | 60 | 60 | 80 | 80 | 86 | 86 |
| Lz | 4.5 | 5.5 | 5.5 | 6.6 | 6.6 | 6.6 | 6.6 |
| LA | 46 | 70 | 70 | 90 | 90 | 100 | 100 |
| s | $\left.8{ }^{(+0.0099}\right)$ | 14( ${ }_{(0.0011}^{+0}$ | 14( ${ }_{(0.0011}^{+0}$ | 14( ${ }_{(0.0011}^{+0}$ | $19\left(\begin{array}{l}\text { (0.013 }\end{array}\right)$ | $16\left({ }_{-0.011}^{+0}\right)$ | $16\left(\begin{array}{l}\text { (0.011 }\end{array}\right)$ |
| LB | 30( ${ }_{-0.021}^{+0}$ ) | $50\left(\begin{array}{c}\text {-0.025 }\end{array}\right.$ | 50( ${ }_{\text {- }}^{\text {+0.025 }}$ ) | 70( ${ }_{-0.030}$ ) | $70\left({ }_{-0.030}\right.$ ) | 80( ${ }_{\text {-0.030 }}$ ) | 80 $\left(\begin{array}{l}\text { (0.030 }\end{array}\right)$ |
| LL ( W/O Brake) | 100.6 | 105.5 | 130.7 | 112.3 | 138.3 | 130.2 | 153.2 |
| LL ( With Brake) | 136.6 | 141.6 | 166.8 | 152.8 | 178 | 161.3 | 184.3 |
| LS (W/o Oil Seal) | 20 | 27 | 27 | 27 | 32 | 30 | 30 |
| LS (With Oil Seal) | 20 | 24 | 24 | 24.5 | 29.5 | 30 | 30 |
| LR | 25 | 30 | 30 | 30 | 35 | 35 | 35 |
| LE | 2.5 | 3 | 3 | 3 | 3 | 3 | 3 |
| LG | 5 | 7.5 | 7.5 | 8 | 8 | 8 | 8 |
| LW | 16 | 20 | 20 | 20 | 25 | 20 | 20 |
| RH | 6.2 | 11 | 11 | 11 | 15.5 | 13 | 13 |
| WK | 3 | 5 | 5 | 5 | 6 | 5 | 5 |
| w | 3 | 5 | 5 | 5 | 6 | 5 | 5 |
| T | 3 | 5 | 5 | 5 | 6 | 5 | 5 |
| TP | $\begin{gathered} \text { M3 } \\ \text { Depth } 8 \end{gathered}$ | $\begin{gathered} \text { M4 } \\ \text { Depth } 15 \end{gathered}$ | $\begin{gathered} \text { M4 } \\ \text { Depth } 15 \end{gathered}$ | $\begin{gathered} \text { M4 } \\ \text { Depth } 15 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \\ \hline \end{gathered}$ | $\begin{gathered} \text { M5 } \\ \text { Depth } 15 \end{gathered}$ | $\begin{gathered} \text { M5 } \\ \text { Depth } 15 \end{gathered}$ |
| ) Dimensions are in millimeters. <br> 2) Dimensions of the servo motors may be revised without prior notice <br> 3) The boxes ( $\square$ ) in the model names are for optional configurations(keyway, brake and oil seal |  |  |  |  |  |  |  |

Speed-Torque Curves (T-N Curves)


## ECMA Series Servo Motors

## Dimensions

## 220V Series

Frame Size 100 mm and 130 mm (Units: mm)


| Model | G11303■S | E11305■S | G11306 ${ }^{\text {S }}$ | G11309■S | C11010】S |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LC | 130 | 130 | 130 | 130 | 100 |
| Lz | 9 | 9 | 9 | 9 | 9 |
| LA | 145 | 145 | 145 | 145 | 115 |
| s | 22( ${ }_{(0.013}$ ) | 22( ${ }_{-0.013}^{+0}$ ) | 22( ${ }_{(0.013}^{+0}$ ) | 22( ${ }_{(0.0013}^{+0}$ | 22( ${ }_{(0.013}^{+0}$ ) |
| LB | $110\left({ }_{-0.035}^{+0}\right)$ | 110( ${ }_{-0.035}^{+0}$ ) | $110\left({ }_{-0.035}\right.$ ) | $110{ }^{+0.035}$ ) | $95\left({ }_{-0.035}^{+0}\right)$ |
| LL ( W/O Brake) | 147.5 | 147.5 | 147.5 | 163.5 | 153.3 |
| LL (With Brake) | 183.5 | 183.5 | 183.5 | 198 | 192.5 |
| Ls | 47 | 47 | 47 | 47 | 37 |
| LR | 55 | 55 | 55 | 55 | 45 |
| LE | 6 | 6 | 6 | 6 | 5 |
| LG | 11.5 | 11.5 | 11.5 | 11.5 | 12 |
| Lw | 36 | 36 | 36 | 36 | 32 |
| RH | 18 | 18 | 18 | 18 | 18 |
| Wk | 8 | 8 | 8 | 8 | 8 |
| w | 8 | 8 | 8 | 8 |  |
| T | 7 | 7 | 7 | 7 | 7 |
| TP | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ |


$>$ TSpeed-Torque Curves (T-N Curves)

21


## Dimensions

## 220V Series

Frame Size 100 mm and 130 mm (Units: mm )


## Speed-Torque Curves (T-N Curves)



## ECMA Series Servo Motors

## Dimensions

## 220V Series

Frame Size 180 mm (Units: mm)


| Model | E11820■S | E11830■S | F11830ПS | F11845 ${ }^{\text {S }}$ | F11855 ${ }^{\text {a }}$ | F11875 $\square^{3}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LC | 180 | 180 | 180 | 180 | 180 | 180 |
| Lz | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 | 13.5 |
| LA | 200 | 200 | 200 | 200 | 200 | 200 |
| s | $35\left(\begin{array}{l}\text { ( } 0.016\end{array}\right)$ | 35 ( ${ }_{-0.016}$ ) | 35( ${ }_{(0.016}^{+0}$ ) | 35( ${ }_{\text {-0.016 }}$ ) | 42( ${ }_{\text {- }}^{\text {-0.016 }}$ ) | 42( ${ }_{-0.016 \text { ) }}$ |
| LB | 114.3 ( ${ }_{-0.035}^{+0}$ ) | $114.3\left(\begin{array}{l}\text { (0.035 }\end{array}\right)$ | 114.3 ${ }_{-0.035}^{+0}$ ) | $114.3\left({ }_{-0.035}^{+0}\right)$ | $114.3\left({ }_{-0.035}^{+0}\right)$ | $114.3{ }^{(+0.035}$ ) |
| LL ( W/O Brake) | 169 | 202.1 | 202.1 | 235.3 | 279.7 | 342.0 |
| LL (With Brake) | 203.1 | 235.3 | 235.3 | 279.3 | 311.7 | 376.1 |
| LS | 73 | 73 | 73 | 73 | 108.5 | 108.5 |
| LR | 79 | 79 | 79 | 79 | 113 | 113 |
| LE | 4 | 4 | 4 | 4 | 4 | 4 |
| LG | 20 | 20 | 20 | 20 | 20 | 20 |
| LW | 63 | 63 | 63 | 63 | 90 | 90 |
| RH | 30 | 30 | 30 | 30 | 37 | 37 |
| WK | 10.0.036 | 10.0 .036 | 10.0 .036 | 10-0.036 | 12.0 .043 | 12.0 .043 |
| w | 10-0.0.36 | $10-0.036$ | $10-0.036$ | 10.0 .036 | ${ }^{12-0.043}$ | 12.0 .043 |
| T | 8 | 8 | 8 | 8 | 8 | 8 |
| TP | $\begin{gathered} \text { M12 } \\ \text { Depth } 25 \end{gathered}$ | $\begin{gathered} \text { M12 } \\ \text { Depth } 25 \end{gathered}$ | $\begin{gathered} \text { M12 } 20 \\ \text { Depth } 25 \\ \hline \end{gathered}$ | $\begin{gathered} \text { M12 } \\ \text { Depth } 25 \end{gathered}$ | $\begin{gathered} \text { M16 } \\ \text { Depth } 32 \end{gathered}$ | $\begin{gathered} \text { M16 } \\ \text { Depth } 32 \end{gathered}$ |


TSpeed-Torque Curves (T-N Curves)


## Dimensions

## 400V Series

Frame Size 80 mm and below (Units: mm )


Speed-Torque Curves (T-N Curves)


## ECMA Series Servo Motors

## Dimensions

## 400V Series

Frame Size 100 mm and 130 mm (Units: mm )


| Model | K11310■S | K11315 $\square$ S | K11320 $\mathrm{S}^{\text {S }}$ |
| :---: | :---: | :---: | :---: |
| LC | 130 | 130 | 130 |
| LZ | 9 | 9 | 9 |
| LA | 145 | 145 | 145 |
| s | $22\left({ }_{-0.013}^{+0}\right)$ | $22\left({ }_{-0.013}^{+0}\right)$ | $22\left({ }_{-0.013}^{+0}\right)$ |
| LB | 110 ( ${ }_{-0.035}^{+0}$ ) | 110 ( ${ }_{-0.035}$ ) | 110( ${ }_{-0.035}$ ) |
| LL ( W/O Brake) | 147.5 | 167.5 | 187.5 |
| LL ( With Brake) | 183.5 | 202 | 216 |
| Ls | 47 | 47 | 47 |
| LR | 55 | 55 | 55 |
| LE | 6 | 6 | 6 |
| LG | 11.5 | 11.5 | 11.5 |
| Lw | 36 | 36 | 36 |
| RH | 18 | 18 | 18 |
| WK | 8 | 8 | 8 |
| w | 8 | 8 |  |
| T | 7 | 7 | 7 |
| TP | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ | $\begin{gathered} \text { M6 } \\ \text { Depth } 20 \end{gathered}$ |
|  | 1) Dimensions are in millimeters <br> 2) Dimensions of the servo motors may be revised without prior notice <br> 3) The boxes $(\square)$ in the model names are for optional configurations(keyway, brake and oil seal). |  |  |

$>$ TSpeed-Torque Curves (T-N Curves)

## Dimensions

## 400V Series

Frame Size 180 mm (Units: mm)


| Model | L11830■S | L11845■S | L11855 ${ }^{3}$ |
| :---: | :---: | :---: | :---: |
| LC | 180 | 180 | 180 |
| Lz | 13.5 | 13.5 | 13.5 |
| LA | 200 | 200 | 200 |
| s | 35( ${ }_{-0.016 \text { ) }}$ | 35 ( ${ }_{-0.016 \text { ) }}$ | 42( ${ }_{-0.016 \text { ) }}$ |
| LB | $114.3\left({ }_{-0.035}^{+0}\right)$ | 114.3 ( ${ }_{-0.035}^{+0}$ ) | 114.3 ( ${ }_{-0.035}^{+0}$ ) |
| LL ( W/O Brake) | 202.1 | 235.3 | 279.7 |
| LL (With Brake) | 235.3 | 279.3 | 311.7 |
| LS | 73 | 73 | 108.5 |
| LR | 79 | 79 | 113 |
| LE | 4 | 4 | 4 |
| LG | 20 | 20 | 20 |
| Lw | 63 | 63 | 90 |
| RH | 30 | 30 | 37 |
| wk | 10.0 .036 | 10 -0.036 | 12.0 .043 |
| w | 10.0 .036 | 10-0.036 | ${ }^{12-0.043}$ |
| T | 8 | 8 | 8 |
| TP | $\begin{gathered} \text { M12 } \\ \text { Depth25 } \end{gathered}$ | $\begin{gathered} \text { M12 } \\ \text { Depth } 25 \end{gathered}$ | $\begin{gathered} \text { M16 } \\ \text { Depth } 32 \\ \hline \end{gathered}$ |

Speed-Torque Curves (T-N Curves)



## Part Names and Functions

- LED Display / Operation Panel / Charge LED
- LED Display

The 5 digit, 7 segment LED displays the servo status or fault codes.

- Operation Panel

Function keys used to perform status display, monitor and diagnostic, function and par
Function Keys:
MODE: Press this key to select SHIFT: Presse mis ke key to shift cursor to the left UP: Press this key to increase values on the display DOWN : Press this key to decrease values on the display SET : Press this key to store data

- Charge LED

A lit LED indicates that either power is connected to
the servo drive or the servo drive or a residual charge
drive's internal power components.

- *Full-Closed Control Interface - Used to connect linear scale and encoder for controlling A, B, Z phase signals.
- I/O Interface

Used to connect Delta's DVP series
PLC or other external controllers for controlling I/O signals.

- *High-speed Communication Port - Used to connect CANopen networks.

1-in/1-out communication ports offer easy serial
nection.
CANbus interface, supporting motion modes for
CANopen DS402 implementation.

- Motor Encoder Interface
- Used to connect the encoder of the servo motor
- Extension Digital Input Connection Port - Used to connect a removable digital input terminal block. Max. 6 digital inputs can be added.
- Serial Communication Port Used to connect PLC, HMI and other controllers for RS-485/RS-232 serial communication.
- USB Connection Port

Used to connect personal computers or notebooks.

- Ver 1.1 USB is equipped as standard.
- Direct connectivity to personal computers or notebooks, capable of accessing data through ASDA-Soft
configuration
- Configuration software. $\quad$ Monitor speed upon software is up to 1 Mbps .
- Internal \& External Regenerative Resistor Terminal / Control Circuit Terminal / Main Circuit Terminal
- Internal \& External Regenerative Resistor Terminal

1. When using an external resistor, connect it to $\mathrm{P} \oplus$ and C , and ensure an open circuit between $\mathrm{P} \oplus$ and D
2. When using an internal resistor, ensure the circuit is closed between $P \oplus$ and $D$, and the circuit is open between $\mathrm{P} \oplus$ and C . (Note: Please refer to the table of regenerative resistor specifications for the models with a built-in regenerative
resistor.)


## Standard Connection Examples

## 220V Series

- Position (PT) Control Mode (for Pulse Command Input)



## 220V Series

- Position (PR) Control Mode (for Internal Procedure Control)



## Standard Connection Examples

## 220V Series

- Speed(S), Torque(T) Control Mode
(for Analog Voltage Input and Internal Parameter Setting)



## 220V Series

- CANopen Communication Mode (for ASDA-A2-M Series)


Standard Connection Examples

## 400V Series

- Position (PT) Control Mode (for Pulse Command Input)



## 400V Series

- Position (PR) Control Mode (for Internal Procedure Control)


[^3]
## Standard Connection Examples

## 400V Series

- Speed(S), Torque(T) Control Mode
(for Analog Voltage Input and Internal Parameter Setting)


Prease note:
*1400w -4.5 kW servo drives provide a built-in regenerative resistor.

## 400V Series

- CANopen Communication Mode (for ASDA-A2-M Series)



## ASDA-SOFT Configuration Software



- Strong CAPTURE and COMPARE functions for position latch and detection help you complete system configuration quickly


User-friendly E-Cam editing interface is provided for designing E-Cam outlines and curves freely. In addition, quick settings for flying shear and rotary cut applications are offered.


Versatile on-line monitoring function, similar to a digital oscilloscope is able to quickly record the status and data of each axis. Real-time monitoring is easy.



- Convenient alarm display function is capable of troubleshooting the system easily and recommending timely corrective actions.

Easy-to-use editing interface is designed for new and enhanced PR control mode. Homing, point-to-point and other motion control functions for multi-axis positioning control are easily achieved.

## ASDA-A2 Series Optional Accessories

- Quick Connectors
- Used for 100 W to 300 W
servo drives
- One operating lever is provided for wire to terminal block insertion.

- Power Cables
- 3 m and 5 m standard cables are available.
- Customized service is offered to meet the needs of customers.
- Two types are selectable: with brake and without brake.

- Encoder Cables
- 3 m and 5 m standard cables are available.
- Customized service is offered to meet the needs of customers.

- RS-232 Communication Cables - Connects ASDA-A2 to PLC, HMI, and other controllers via RS-232
communication.
- Standard cable length is 3 m .


- Terminal Block Modules - Easy installation and wiring - 0.5 m connection cable is provided. Easy to reduce the space required.
- Easy to expand system's I/O configuration.
- Regenerative Resistors
- For selecting a regenerative resistor please refer to the table of regenerative resistor specifications on page 62
- USB Communication Cables (for PC)
- Connects ASDA-A2 to a PC (via ASDA-Soft configuration software) - USB1 1 is equipped as standard
- CANopen Accessories
- Delta's TAP-CN03 distribution box connects ASDA-A2 to Delta's PLC CAN Master.
- CANopen communication cable is provided. Standard cable length is 0.5 m and 1 m .

- RS-485 Connectors
- Used to connect multiple ASDA-A2 series products by RS-485 interface series products by RS-485 interface
through Modbus serial communication.


Dimensions

## 220V Series

100W / 200W / 400W

750W / 1.0kW / 1.5kW

Weight
$2.0 \mathrm{~kW} / 3.0 \mathrm{~kW}$
2.89 (6.3)


D Dimensions

## 220V Series

4.5 kW
4.4 (10.0)


Dimensions

## 400V Series

750W / 1.0kW / 1.5kW

2.0kW / 3.0kW / $4.5 \mathrm{~kW} / 5.5 \mathrm{~kW}$


- Power Connectors

ASD-CAPW

MS 3106A-24-11S
ASD-CAPW4000


ASD-CNBR1000


CLAMP: WPS3106A 10SL-4S-R

- Power Cables


ASDA-A2 Optional Accessories

OOptional Accessories


ASD-A2PW1003, ASD-A2PW1005


ASD-CAPW1203/1205


ASD-CAPW2003, ASD-CAPW2005


ASD-CAPW2103, ASD-CAPW2105


ASD-CAPW2203, ASD-CAPW2205


## ASDA-A2 Optional Accessories

## Optional Accessories

- Power Cables

- Encoder Connectors ASD-ABEN0000



## ASD-CNSC0050



## Optional Accessories

－Terminal Block Module
ASD－BM－50A

－RS－232 Communication Cable

－Communication Cable between Drive and Computer（for PC）

－CANopen Communication Cable TAP－CB03，TAP－CB04

－CANopen Distribution Box
TAP－CN03

$\square$ NOTE ${ }^{\text {1）}}$（ther accessories for ${ }^{\text {increased }}$ ASDA－A2 series will beally．


## Servo Drive，Servo Motor and Accessories Combinations

## 220V Series

100W Servo Drive and 100W Low Inertia Servo Motor

| Servo Drive | ASD－A2－0121－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia Servo Motor | ECMA－C10401ロ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－ABPW0003 | Power－Cables ASD－ABPW0005 | Power－Cables ASD－ABPW0103 | Power－Cables ASD－ABPW0105 |
|  | Encoder Cables <br> ASD－ABENOOO3 | Encoder Cables <br> ASD－ABEN0005 | Encoder Cables <br> ASD－ABENOOO3 | Encoder Cables <br> ASD－ABENOOO5 |
| Connector | Power Connector | ASDBCAPW0000 | Power Connector | ASDBCAPW0100 |

200W Servo Drive and 200W Low Inertia Servo Motor

| Servo Drive | ASD－A2－0221－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia | ECMA－C10602ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3 M | 5M | 3 M | 5M |
|  | Power－Cables ASD－ABPW0003 | Power－Cables ASD－ABPW0005 | Power－Cables ASD－ABPW0103 | Power－Cables ASD－ABPW0105 |
|  | Encoder Cables ASD－ABEN0003 | Encoder Cables ASD－ABEN0005 | Encoder Cables ASD－ABEN0003 | Encoder Cables ASD－ABEN0005 |
| Connector | Power Connectors ASDBCAPW0000 |  | Power Connectors ASDBCAPW0100 |  |
|  | Encoder Cables ASD－ABENOOOO |  |  |  |

400W Servo Drive and 400W Low Inertia Servo Motor

| Servo Drive | ASD－A2－0421－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia Servo Motor | ECMA－C10604ロS ECMA－C10804ロ7 |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－ABPW0003 | Power－Cables ASD－ABPW0005 | Power－Cables ASD－ABPW0103 | Power－Cables ASD－ABPW0105 |
|  | Encoder Cables ASD－ABEN0003 | Encoder Cables ASD－ABEN0005 | Encoder Cables ASD－ABENOOO3 | Encoder Cables ASD－ABEN0005 |
| Connector | Power Connectors ASDBCAPW0000 |  | Power Connectors ASDBCAPW0100 |  |
|  | Encoder Cables ASD－ABENOOOO |  |  |  |

## Servo Drive，Servo Motor and Accessories Combinations

## 220V Series

400W Servo Drive and 500W Medium Inertia Servo Motor

| Servo Drive | ASD－A2－0421－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia Servo Motor | ECMA－E11305ロ S |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW1000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

750W Servo Drive and 600W High Inertia Servo Motor

| Servo Drive | ASD－A2－0721－ロ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| High Inertia |  |  |  |  |  |
| Servo Motor |  |  |  |  |  |

1kW Servo Drive and 1kW Low Inertia Servo Motor
400W Servo Drive and 300W High Inertia Servo Motor

| Servo Drive | ASD－A2－0421－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| High Inertia Servo Motor | ECMA－G11303口S |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| onnector | Power Connectors ASD－CAPW1000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |


| Servo Drive | ASD－A2－1021－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia Servo Motor | ECMA－C11010ロS |  |  |  |
|  | ECMA－C10910ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
|  | Power Connectors ASD－CAPW1000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |

750W Servo Drive and 750W Low Inertia Servo Motor

| Servo Drive | ASD－A2－0721－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia Servo Motor | ECMA－C10807■ S |  |  |  |
|  | ECMA－C10907ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－ABPW0003 | Power－Cables ASD－ABPW0005 | Power－Cables ASD－ABPW0103 | Power－Cables ASD－ABPW0105 |
|  | Encoder Cables ASD－ABEN0003 | Encoder Cables ASD－ABEN0005 | Encoder Cables ASD－ABEN0003 | Encoder Cables ASD－ABEN0005 |
| Connector | Power Connectors ASDBCAPW0000 |  | Power Connectors ASDBCAPW0100 |  |
|  | Encoder Cables ASD－ABENOOOO |  |  |  |

1kW Servo Drive and 1kW Medium Inertia Servo Motor

| Servo Drive | ASD－A2－1021－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia | ECMA－E11310ロ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW1000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

## Servo Drive，Servo Motor and Accessories Combinations

## 220V Series

1 kW Servo Drive and 900W High Inertia Servo Motor

| Servo Drive | ASD－A2－1021－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| High Inertia Servo Motor | ECMA－G11309ロ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW1000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

1．5kW Servo Drive and 1．5kW Medium Inertia Servo Motor

| Servo Drive | ASD－A2－1521－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia Servo Motor | ECMA－E11315ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
|  | Power Connectors ASD－CAPW1000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |

2kW Servo Drive and 2kW Low Inertia Servo Motor

| Servo Drive | ASD－A2－2023－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia | ECMA－C11020ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－A2PW1003 | Power－Cables ASD－A2PW1005 | Power－Cables ASD－A2PW1103 | Power－Cables ASD－A2PW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables <br> ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW1000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

2kW Servo Drive and 2kW Medium Inertia Servo Motor

| Servo Drive | AsD－A2－2023－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia Servo Motor | ECMA－E11320ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－A2PW1003 | Power－Cables ASD－A2PW1005 | Power－Cables ASD－A2PW1103 | Power－Cables ASD－A2PW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
|  | Power Connectors ASD－CAPW1000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |

$\mathbf{2 k W}$ Servo Drive and 2kW Medium Inertia Servo Motor

| Servo Drive | ASD－A2－2023－ロ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia |  |  |  |  |
| Servo Motor |  |  |  |  |

3kW Servo Drive and 3kW Medium Inertia Servo Motor

| Servo Drive | ASD－A2－3023－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia Servo Motor | ECMA－E11830ロS |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW2003 | Power－Cables ASD－CAPW2005 | Power－Cables ASD－CAPW2103 | Power－Cables ASD－CAPW2105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW2000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |



## Servo Drive，Servo Motor and Accessories Combinations

## 220V Series

3kW Servo Drive and 3kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－3023－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium－High Inertia Servo Motor | ECMA－F11830ロ S |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW2003 | Power－Cables ASD－CAPW2005 | Power－Cables ASD－CAPW2103 | Power－Cables ASD－CAPW2105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW2000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |

4．5kW Servo Drive and 4.5 kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－4523－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium－High Inertia Servo Motor | ECMA－F11845■ S |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW3203 | Power－Cables ASD－CAPW3205 | Power－Cables ASD－CAPW3303 | Power－Cables ASD－CAPW3305 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW2000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

5.5 kW Servo Drive and 5.5 kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－5523－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium－High Inertia Servo Motor | ECMA－F11855ロ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | － | － | － | － |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW4000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |
|  | Brake Cables ASD－CNBR1000 |  |  |  |

220V Series
7．5kW Servo Drive and 7．5kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－7523－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium－High Inertia Servo Motor | ECMA－F11875］ 3 |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | － | － | － |  |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW4000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |
|  | Brake Cables ASD－CNBR1000 |  |  |  |

400V Series
750W Servo Drive and 750W Low Inertia Servo Motor

| Servo Drive | ASD－A2－0743－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Low Inertia | ECMA－J10807ロ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－ABPW0003 | Power－Cables ASD－ABPW0005 | Power－Cables ASD－ABPW0103 | Power－Cables ASD－ABPW0105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| onnector | Power Connectors ASDBCAPW0000 |  | Power Connectors ASDBCAPW0100 |  |
|  | Encoder Cables ASD－ABENOOOO |  |  |  |

1kW Servo Drive and 1kW Medium Inertia Servo Motor

| Servo Drive | ASD－A2－1043－■ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Medium Inertia |  |  |  |  |  |
| Servo Motor |  |  |  |  |  |

## Servo Drive，Servo Motor and Accessories Combinations

## 400V Series

1．5kW Servo Drive and 1．5kW Medium Inertia Servo Motor

| Servo Drive | ASD－A2－1543－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia Servo Motor | ECMA－K11315ロ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW1003 | Power－Cables ASD－CAPW1005 | Power－Cables ASD－CAPW1103 | Power－Cables ASD－CAPW1105 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW1000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

4．5kW Servo Drive and 4.5 kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－4543－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium－High Inertia Servo Motor | ECMA－L11845ロ ${ }^{\text {S }}$ |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW2203 | Power－Cables ASD－CAPW2205 | Power－Cables ASD－CAPW2303 | Power－Cables ASD－CAPW2305 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW2000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

5．5kW Servo Drive and 5．5kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－2043－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium Inertia Servo Motor | ECMA－K11320ロ S |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5 M |
|  | Power－Cables ASD－CAPW1203 | Power－Cables ASD－CAPW1205 | Power－Cables ASD－CAPW1303 | Power－Cables ASD－CAPW1305 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
|  | Power Connectors ASD－CAPW1000 |  |  |  |
| Connector | Encoder Cables ASD－CAEN1000 |  |  |  |


| Servo Drive | ASD－A2－5543－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | ECMA－L11855－3 |  |  |  |
|  | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
| Cable | Power－Cables ASD－CAPW2203 | Power－Cables ASD－CAPW2205 | Power－Cables ASD－CAPW2303 | Power－Cables ASD－CAPW2305 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW2000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |

3kW Servo Drive and 3kW Medium－High Inertia Servo Motor

| Servo Drive | ASD－A2－3043－■ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Medium－High Inertia Servo Motor | ECMA－L11830－S |  |  |  |
| Cable | Without Brake |  | With Brake |  |
|  | 3M | 5M | 3M | 5M |
|  | Power－Cables ASD－CAPW2203 | Power－Cables ASD－CAPW2205 | Power－Cables ASD－CAPW2303 | Power－Cables ASD－CAPW2305 |
|  | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 | Encoder Cables ASD－CAEN1003 | Encoder Cables ASD－CAEN1005 |
| Connector | Power Connectors ASD－CAPW2000 |  |  |  |
|  | Encoder Cables ASD－CAEN1000 |  |  |  |



Servo Drive, Servo Motor and Accessories Combinations

| Other Accessories (for ASDA-A2 series all models) |  |
| :---: | :---: |
| Description | Delta Part Number |
| 50Pin I/O signal connector (Cn1) | ASD-CNSC0050 |
| Terminal Block Module | ASD-BM-50A |
| RS-232 Communication Cable | ASD-CARS0003 |
| Communication Cable between Drive and Computer(for PC) | DOP-CAUSBAB |
| CANopen Communication Cable | TAP-CB03/TAP-CB04 |
| CANopen Distribution Box | TAP-CN03 |
| RS-485 Connector | ASD-CNIE0B06 |
| Regenerative Resistor 400W 40 | BR400W040 |
| Regenerative Resistor 1kW $20 \Omega$ | BR1K0W020 |
| Regenerative Resistor $3 \mathrm{~kW} 10 \Omega$ | BR1K5W005 |

## Safety Information

| Global Standards | ASDA-A2 series is designed to fully comply with demanding international standards, i.e. IEC and EN, etc. for all fields of industrial automation technology. |  |
| :---: | :---: | :---: |
| EMS standard | EN61000-4-6 | Level 3 |
|  | EN61000-4-3 | Level 3 |
|  | EN61000-4-2 | Level 2 and Level 3 |
|  | EN61000-4-4 | Level 3 |
|  | EN61000-4-8 | Level 4 |
|  | EN61000-4-5 | Levelv3 |
| Conducted \& Radiated Emissions | Complies with EN550011 Class A Group 1, with external EMC filter |  |
| CE Marking | CE recognized. Complies with Directive 2006/95/EC of the European Parliament and EMC Directive 2004/108/EC. |  |
| ULApproval | UL (U.S.), cUL (Canada) recognized. |  |
| Test Standard | IEC/EN50178, IEC/EN60529 |  |
|  | IP20 |  |
| Vibration | 1 G less than $20 \mathrm{~Hz}, 0.6 \mathrm{G} 20$ to 50 Hz . Complies with IEC/EN50178 |  |
| Shock | 15 gn 11 ms . Complies with IEC/EN600028-2-27 |  |
| Pollution Degree | Degree 2. Complies with IEC/EN61800-5-1 |  |
| IEC: International Electrotechnical Commission <br> EN: Europaischen Normen <br> EMC: Electromagnetic Compatibility <br> IP: Ingress Protection Ratings |  |  |

Regenerative Resistor Specifications

## 220V Series

| Servo Drive (kW) | Specifications of Built-in Regenerative Resistors <br> (parameter P1-52) (Ohm) | Capaity <br> (parameter P1-53) (Watt) | Min. Allowable Resistance <br> (Ohm) |
| :---: | :---: | :---: | :---: |
|  | - | - | $30 \Omega$ |
|  | - | - | $30 \Omega$ |
| 0.4 | $40 \Omega$ | 40 W | $30 \Omega$ |
| 0.75 | $40 \Omega$ | 60 W | $20 \Omega$ |
| 1.0 | $40 \Omega$ | 60 W | $20 \Omega$ |
| 1.5 | $40 \Omega$ | 60 W | $20 \Omega$ |
| 2.0 | $20 \Omega$ | 100 W | $10 \Omega$ |
| 3.0 | $20 \Omega$ | 100 W | $10 \Omega$ |
| 4.5 | $20 \Omega$ | 100 W | $10 \Omega$ |
| $5.5 / 7.5$ | - | - | $8 \Omega$ |

- $400 \mathrm{~W} \sim 4.5 \mathrm{~kW}$ servo drives provide a built-in regenerative resistor
- When the fault, ALE05 (Regeneration Error) occurs, please increase the regenerative resistor
capacity or decrease the regenerative resistor resistance (the regenerative resistor resistanc
should
Note:
- If the situation is not improved after increasing the regenerative resistor capacity or
- When combiningenerative resistor resistance, please purchase regenerative resistor
- When combining multiple small-capacity regenerative resistors in parallel to increase the
regenerative e esistor capacity
shake sure that the total resistance value of the regenerative resistors
regenerative resistor capacity, make sure that the totar resistance value of the regen
should not be less than the minimum allowable resistance listed in the above table.
400V Series

| Servo Drive (kW) | Specifications of Built-in Regenerative Resistors |  | Min. Allowable Resistance (Ohm) |
| :---: | :---: | :---: | :---: |
|  | Resistance <br> (parameter P1-52) (Ohm) | Capacity (parameter P1-53) (Watt) |  |
| 0.75 | $80 \Omega$ | 100w | $60 \Omega$ |
| 1.0 | $80 \Omega$ | 100w | $60 \Omega$ |
| 1.5 | $80 \Omega$ | 100w | $40 \Omega$ |
| 2.0 | - |  | $40 \Omega$ |
| 3.0 | - | - | $30 \Omega$ |
| 4.5 | - | - | $20 \Omega$ |
| 5.5 | - | - | $20 \Omega$ |
| Note: | - 750W $\sim 1.5 \mathrm{~kW}$ servo drives provide a built-in regenerative resistor. <br> - When the fault, ALE05 (Regeneration Error) occurs, please increase the regenerative resistor capacity or decrease the regenerative resistor resistance (the regenerative resistor resistance should not be less than the minimum allowable resistance listed in the above table.) |  |  |
|  | When combining multiple small-capacity regenerative resistors in parallel to increase the regenerative resistor capacity, make sure that the total resistance value of the regenerative resistors should not be less than the minimum allowable resistance listed in the above table. |  |  |


[^0]:    
    
    

[^1]:    
    

[^2]:    Nome
    
    ECMA: $18: 550 \mathrm{~mm} \times 550 \mathrm{~mm} \times 30 \mathrm{~mm}$. $\mathrm{F} 100, \mathrm{~F} 30$, F180

[^3]:    

